Table of Information and Equation Tables for AP Physics Exams

The accompanying Table of Information and Equation Tables will be provided to students when they take the AP Physics Exams. Therefore, students may NOT bring their own copies of these tables to the exam room, although they may use them throughout the year in their classes in order to become familiar with their content.

Table of Information

For both the Physics B and Physics C Exams, the Table of Information is printed near the front cover of the multiple-choice section and on the green insert provided with the free-response section. The tables are identical for both exams except for one convention as noted.

Equation Tables

For both the Physics B and Physics C Exams, the equation tables for each exam are printed only on the green insert provided with the free-response section. The equation tables may be used by students when taking the free-response sections of both exams but NOT when taking the multiple-choice sections.

The equations in the tables express the relationships that are encountered most frequently in AP Physics courses and exams. However, the tables do not include all equations that might possibly be used. For example, they do not include many equations that can be derived by combining other equations in the tables. Nor do they include equations that are simply special cases of any that are in the tables. Students are responsible for understanding the physical principles that underlie each equation and for knowing the conditions for which each equation is applicable.

The equation tables are grouped in sections according to the major content category in which they appear. Within each section, the symbols used for the variables in that section are defined. However, in some cases the same symbol is used to represent different quantities in different tables. It should be noted that there is no uniform convention among textbooks for the symbols used in writing equations. The equation tables follow many common conventions, but in some cases consistency was sacrificed for the sake of clarity.

Some explanations about notation used in the equation tables:

1. The symbols used for physical constants are the same as those in the Table of Information and are defined in the Table of Information rather than in the right-hand columns of the tables.
2. Symbols in bold face represent vector quantities.
3. Subscripts on symbols in the equations are used to represent special cases of the variables defined in the right-hand columns.
4. The symbol Δ before a variable in an equation specifically indicates a change in the variable (i.e., final value minus initial value).
5. Several different symbols (e.g., d, r, s, h, ℓ) are used for linear dimensions such as length. The particular symbol used in an equation is one that is commonly used for that equation in textbooks.

TABLE OF INFORMATION FOR 2006 and 2007

CONSTANTS AND CONVERSION FACTORS

1 unified atomic mass unit,	$1\ \text{u} = 1.66 \times 10^{-27}\ \text{kg}$
	$= 931\ \text{MeV}/c^2$
Proton mass,	$m_p = 1.67 \times 10^{-27}\ \text{kg}$
Neutron mass,	$m_n = 1.67 \times 10^{-27}\ \text{kg}$
Electron mass,	$m_e = 9.11 \times 10^{-31}\ \text{kg}$
Electron charge magitude,	$e = 1.60 \times 10^{-19}\ \text{C}$
Avogadro's number,	$N_0 = 6.02 \times 10^{23}\ \text{mol}^{-1}$
Universal gas constant,	$R = 8.31\ \text{J/(mol•K)}$
Boltzmann's constant,	$k_B = 1.38 \times 10^{-23}\ \text{J/K}$
Speed of light,	$c = 3.00 \times 10^8\ \text{m/s}$
Planck's constant,	$h = 6.63 \times 10^{-34}\ \text{J•s}$
	$= 4.14 \times 10^{-15}\ \text{eV•s}$
	$hc = 1.99 \times 10^{-25}\ \text{J•m}$
	$= 1.24 \times 10^3\ \text{eV•nm}$
Vacuum permittivity,	$\epsilon_0 = 8.85 \times 10^{-12}\ \text{C}^2/\text{N•m}^2$
Coulomb's law constant,	$k = 1/4\pi\epsilon_0 = 9.0 \times 10^9\ \text{N•m}^2/\text{C}^2$
Vacuum permeability,	$\mu_0 = 4\pi \times 10^{-7}\ \text{(T•m)/A}$
Magnetic constant,	$k' = \mu_0/4\pi = 10^{-7}\ \text{(T•m)/A}$
Universal gravitational constant,	$G = 6.67 \times 10^{-11}\ \text{m}^3/\text{kg•s}^2$
Acceleration due to gravity at Earth's surface,	$g = 9.8\ \text{m/s}^2$
1 atmosphere pressure,	$1\ \text{atm} = 1.0 \times 10^5\ \text{N/m}^2$
	$= 1.0 \times 10^5\ \text{Pa}$
1 electron volt,	$1\ \text{eV} = 1.60 \times 10^{-19}\ \text{J}$

UNITS

Name	Symbol
meter	m
kilogram	kg
second	s
ampere	A
kelvin	K
mole	mol
hertz	Hz
newton	N
pascal	Pa
joule	J
watt	W
coulomb	C
volt	V
ohm	Ω
henry	H
farad	F
tesla	T
degree Celsius	°C
electron-volt	eV

PREFIXES

Factor	Prefix	Symbol
10^9	giga	G
10^6	mega	M
10^3	kilo	k
10^{-2}	centi	c
10^{-3}	milli	m
10^{-6}	micro	μ
10^{-9}	nano	n
10^{-12}	pico	p

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES

θ	sin θ	cos θ	tan θ
0°	0	1	0
30°	1/2	$\sqrt{3}/2$	$\sqrt{3}/3$
37°	3/5	4/5	3/4
45°	$\sqrt{2}/2$	$\sqrt{2}/2$	1
53°	4/5	3/5	4/3
60°	$\sqrt{3}/2$	1/2	$\sqrt{3}$
90°	1	0	∞

The following conventions are used in this examination.

I. Unless otherwise stated, the frame of reference of any problem is assumed to be inertial.
II. The direction of any electric current is the direction of flow of positive charge (conventional current).
III. For any isolated electric charge, the electric potential is defined as zero at an infinite distance from the charge.
*IV. For mechanics and thermodynamics equations, *W* represents the work done <u>on</u> a system.

*Not on the Table of Information for Physics C, since Thermodynamics is not a Physics C topic.

ADVANCED PLACEMENT PHYSICS B EQUATIONS FOR 2006 and 2007

NEWTONIAN MECHANICS

$$\upsilon = \upsilon_0 + at$$

$$x = x_0 + \upsilon_0 t + \frac{1}{2}at^2$$

$$\upsilon^2 = \upsilon_0^{\,2} + 2a(x - x_0)$$

$$\sum \mathbf{F} = \mathbf{F}_{net} = m\mathbf{a}$$

$$F_{fric} \le \mu N$$

$$a_c = \frac{\upsilon^2}{r}$$

$$\tau = rF \sin\theta$$

$$\mathbf{p} = m\mathbf{v}$$

$$\mathbf{J} = \mathbf{F}\Delta t = \Delta\mathbf{p}$$

$$K = \frac{1}{2}m\upsilon^2$$

$$\Delta U_g = mgh$$

$$W = F\Delta r \cos\theta$$

$$P_{avg} = \frac{W}{\Delta t}$$

$$P = F\upsilon\cos\theta$$

$$\mathbf{F}_s = -k\mathbf{x}$$

$$U_s = \frac{1}{2}kx^2$$

$$T_s = 2\pi\sqrt{\frac{m}{k}}$$

$$T_p = 2\pi\sqrt{\frac{\ell}{g}}$$

$$T = \frac{1}{f}$$

$$F_G = -\frac{Gm_1m_2}{r^2}$$

$$U_G = -\frac{Gm_1m_2}{r}$$

- a = acceleration
- F = force
- f = frequency
- h = height
- J = impulse
- K = kinetic energy
- k = spring constant
- ℓ = length
- m = mass
- N = normal force
- P = power
- p = momentum
- r = radius or distance
- T = period
- t = time
- U = potential energy
- υ = velocity or speed
- W = work done on a system
- x = position
- μ = coefficient of friction
- θ = angle
- τ = torque

ELECTRICITY AND MAGNETISM

$$F = \frac{1}{4\pi\epsilon_0}\frac{q_1q_2}{r^2}$$

$$\mathbf{E} = \frac{\mathbf{F}}{q}$$

$$U_E = qV = \frac{1}{4\pi\epsilon_0}\frac{q_1q_2}{r}$$

$$E_{avg} = -\frac{V}{d}$$

$$V = \frac{1}{4\pi\epsilon_0}\sum_i \frac{q_i}{r_i}$$

$$C = \frac{Q}{V}$$

$$C = \frac{\epsilon_0 A}{d}$$

$$U_c = \frac{1}{2}QV = \frac{1}{2}CV^2$$

$$I_{avg} = \frac{\Delta Q}{\Delta t}$$

$$R = \frac{\rho\ell}{A}$$

$$V = IR$$

$$P = IV$$

$$C_p = \sum_i C_i$$

$$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$$

$$R_s = \sum_i R_i$$

$$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$$

$$F_B = q\upsilon B\sin\theta$$

$$F_B = BI\ell\sin\theta$$

$$B = \frac{\mu_0}{2\pi}\frac{I}{r}$$

$$\phi_m = BA\cos\theta$$

$$\varepsilon_{avg} = -\frac{\Delta\phi_m}{\Delta t}$$

$$\varepsilon = B\ell\upsilon$$

- A = area
- B = magnetic field
- C = capacitance
- d = distance
- E = electric field
- ε = emf
- F = force
- I = current
- ℓ = length
- P = power
- Q = charge
- q = point charge
- R = resistance
- r = distance
- t = time
- U = potential (stored) energy
- V = electric potential or potential difference
- υ = velocity or speed
- ρ = resistivity
- θ = angle
- ϕ_m = magnetic flux

ADVANCED PLACEMENT PHYSICS B EQUATIONS FOR 2006 and 2007

FLUID MECHANICS AND THERMAL PHYSICS

$P = P_0 + \rho g h$

$F_{buoy} = \rho V g$

$A_1 v_1 = A_2 v_2$

$P + \rho g y + \frac{1}{2}\rho v^2 = \text{const.}$

$\Delta \ell = \alpha \ell_0 \Delta T$

$H = \dfrac{kA\,\Delta T}{L}$

$P = \dfrac{F}{A}$

$PV = nRT = Nk_B T$

$K_{avg} = \frac{3}{2} k_B T$

$v_{rms} = \sqrt{\dfrac{3RT}{M}} = \sqrt{\dfrac{3k_B T}{\mu}}$

$W = -P\Delta V$

$\Delta U = Q + W$

$e = \left| \dfrac{W}{Q_H} \right|$

$e_c = \dfrac{T_H - T_C}{T_H}$

A = area
e = efficiency
F = force
h = depth
H = rate of heat transfer
k = thermal conductivity
K_{avg} = average molecular kinetic energy
ℓ = length
L = thickness
M = molar mass
n = number of moles
N = number of molecules
P = pressure
Q = heat transferred to a system
T = temperature
U = internal energy
V = density
v = velocity or speed
v_{rms} = root-mean-square velocity
W = work done on a system
y = height
α = coefficient of linear expansion
μ = mass of molecule
ρ = density

ATOMIC AND NUCLEAR PHYSICS

$E = hf = pc$

$K_{\max} = hf - \phi$

$\lambda = \dfrac{h}{p}$

$\Delta E = (\Delta m)c^2$

E = energy
f = frequency
K = kinetic energy
m = mass
p = momentum
λ = wavelength
ϕ = work function

WAVES AND OPTICS

$v = f\lambda$

$n = \dfrac{c}{v}$

$n_1 \sin\theta_1 = n_2 \sin\theta_2$

$\sin\theta_c = \dfrac{n_2}{n_1}$

$\dfrac{1}{s_i} + \dfrac{1}{s_0} = \dfrac{1}{f}$

$M = \dfrac{h_i}{h_0} = -\dfrac{s_i}{s_0}$

$f = \dfrac{R}{2}$

$d\sin\theta = m\lambda$

$x_m \sim \dfrac{m\lambda L}{d}$

d = separation
f = frequency or focal length
h = height
L = distance
M = magnification
m = an integer
n = index of refraction
R = radius of curvature
s = distance
v = speed
x = position
λ = wavelength
θ = angle

GEOMETRY AND TRIGONOMETRY

Rectangle
$A = bh$

Triangle
$A = \frac{1}{2}bh$

Circle
$A = \pi r^2$
$C = 2\pi r$

Parallelepiped
$V = \ell wh$

Cylinder
$V = \pi r^2 \ell$
$S = 2\pi r\ell + 2\pi r^2$

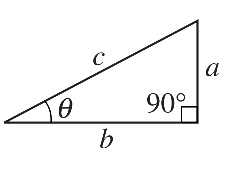
Sphere
$V = \frac{4}{3}\pi r^3$
$S = 4\pi r^2$

Right Triangle
$a^2 + b^2 = c^2$

$\sin\theta = \dfrac{a}{c}$

$\cos\theta = \dfrac{b}{c}$

$\tan\theta = \dfrac{a}{b}$



A = area
C = circumference
V = volume
S = surface area
b = base
h = height
ℓ = length
w = width
r = radius

ADVANCED PLACEMENT PHYSICS C EQUATIONS FOR 2006 and 2007

MECHANICS

$\upsilon = \upsilon_0 + at$

$x = x_0 + \upsilon_0 t + \frac{1}{2}at^2$

$\upsilon^2 = \upsilon_0^2 + 2a(x - x_0)$

$\sum \mathbf{F} = \mathbf{F}_{net} = m\mathbf{a}$

$\mathbf{F} = \frac{d\mathbf{p}}{dt}$

$\mathbf{J} = \int \mathbf{F}\, dt = \Delta\mathbf{p}$

$\mathbf{p} = m\mathbf{v}$

$F_{fric} \le \mu N$

$W = \int \mathbf{F} \cdot d\mathbf{r}$

$K = \frac{1}{2}m\upsilon^2$

$P = \frac{dW}{dt}$

$P = \mathbf{F} \cdot \mathbf{v}$

$\Delta U_g = mgh$

$a_c = \frac{\upsilon^2}{r} = \omega^2 r$

$\boldsymbol{\tau} = \mathbf{r} \times \mathbf{F}$

$\sum \boldsymbol{\tau} = \boldsymbol{\tau}_{net} = I\boldsymbol{\alpha}$

$I = \int r^2 dm = \sum mr^2$

$\mathbf{r}_{cm} = \sum m\mathbf{r} / \sum m$

$\upsilon = r\omega$

$\mathbf{L} = \mathbf{r} \times \mathbf{p} = I\boldsymbol{\omega}$

$K = \frac{1}{2}I\omega^2$

$\omega = \omega_0 + \alpha t$

$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$

a = acceleration
F = force
f = frequency
h = height
I = rotational inertia
J = impulse
K = kinetic energy
k = spring constant
ℓ = length
L = angular momentum
m = mass
N = normal force
P = power
p = momentum
r = radius or distance
$\mathbf{r}$ = position vector
T = period
t = time
U = potential energy
υ = velocity or speed
W = work done on a system
x = position
μ = coefficient of friction
θ = angle
τ = torque
ω = angular speed
α = angular acceleration

$\mathbf{F}_s = -k\mathbf{x}$

$U_s = \frac{1}{2}kx^2$

$T = \frac{2\pi}{\omega} = \frac{1}{f}$

$T_s = 2\pi\sqrt{\frac{m}{k}}$

$T_p = 2\pi\sqrt{\frac{\ell}{g}}$

$\mathbf{F}_G = -\frac{Gm_1m_2}{r^2}\hat{\mathbf{r}}$

$U_G = -\frac{Gm_1m_2}{r}$

ELECTRICITY AND MAGNETISM

$F = \frac{1}{4\pi\epsilon_0}\frac{q_1q_2}{r^2}$

$\mathbf{E} = \frac{\mathbf{F}}{q}$

$\oint \mathbf{E} \cdot d\mathbf{A} = \frac{Q}{\epsilon_0}$

$E = -\frac{dV}{dr}$

$V = \frac{1}{4\pi\epsilon_0}\sum_i \frac{q_i}{r_i}$

$U_E = qV = \frac{1}{4\pi\epsilon_0}\frac{q_1q_2}{r}$

$C = \frac{Q}{V}$

$C = \frac{\kappa\epsilon_0 A}{d}$

$C_p = \sum_i C_i$

$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$

$I = \frac{dQ}{dt}$

$U_c = \frac{1}{2}QV = \frac{1}{2}CV^2$

$R = \frac{\rho\ell}{A}$

$\mathbf{E} = \rho\mathbf{J}$

$I = Nev_d A$

$V = IR$

$R_s = \sum_i R_i$

$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$

$P = IV$

$\mathbf{F}_M = q\mathbf{v} \times \mathbf{B}$

A = area
B = magnetic field
C = capacitance
d = distance
E = electric field
$\mathcal{E}$ = emf
F = force
I = current
J = current density
L = inductance
ℓ = length
n = number of loops of wire per unit length
N = number of charge carriers per unit volume
P = power
Q = charge
q = point charge
R = resistance
r = distance
t = time
U = potential or stored energy
V = electric potential
υ = velocity or speed
ρ = resistivity
ϕ_m = magnetic flux
κ = dielectric constant

$\oint \mathbf{B} \cdot d\boldsymbol{\ell} = \mu_0 I$

$d\mathbf{B} = \frac{\mu_0}{4\pi}\frac{I\, d\boldsymbol{\ell} \times \mathbf{r}}{r^3}$

$\mathbf{F} = \int I\, d\boldsymbol{\ell} \times \mathbf{B}$

$B_s = \mu_0 nI$

$\phi_m = \int \mathbf{B} \cdot d\mathbf{A}$

$\mathcal{E} = -\frac{d\phi_m}{dt}$

$\mathcal{E} = -L\frac{dI}{dt}$

$U_L = \frac{1}{2}LI^2$

ADVANCED PLACEMENT PHYSICS C EQUATIONS FOR 2006 and 2007

GEOMETRY AND TRIGONOMETRY

Rectangle

$A = bh$

Triangle

$A = \frac{1}{2}bh$

Circle

$A = \pi r^2$

$C = 2\pi r$

Parallelepiped

$V = \ell wh$

Cylinder

$V = \pi r^2 \ell$

$S = 2\pi r\ell + 2\pi r^2$

Sphere

$V = \frac{4}{3}\pi r^3$

$S = 4\pi r^2$

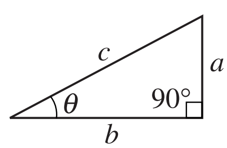
Right Triangle

$a^2 + b^2 = c^2$

$\sin\theta = \frac{a}{c}$

$\cos\theta = \frac{b}{c}$

$\tan\theta = \frac{a}{b}$



A = area
C = circumference
V = volume
S = surface area
b = base
h = height
ℓ = length
w = width
r = radius

CALCULUS

$$\frac{df}{dx} = \frac{df}{du}\frac{du}{dx}$$

$$\frac{d}{dx}\left(x^n\right) = nx^{n-1}$$

$$\frac{d}{dx}\left(e^x\right) = e^x$$

$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$

$$\frac{d}{dx}(\sin x) = \cos x$$

$$\frac{d}{dx}(\cos x) = -\sin x$$

$$\int x^n\,dx = \frac{1}{n+1}x^{n+1},\ n \neq -1$$

$$\int e^x\,dx = e^x$$

$$\int \frac{dx}{x} = \ln|x|$$

$$\int \cos x\,dx = \sin x$$

$$\int \sin x\,dx = -\cos x$$